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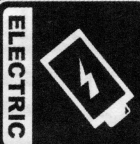
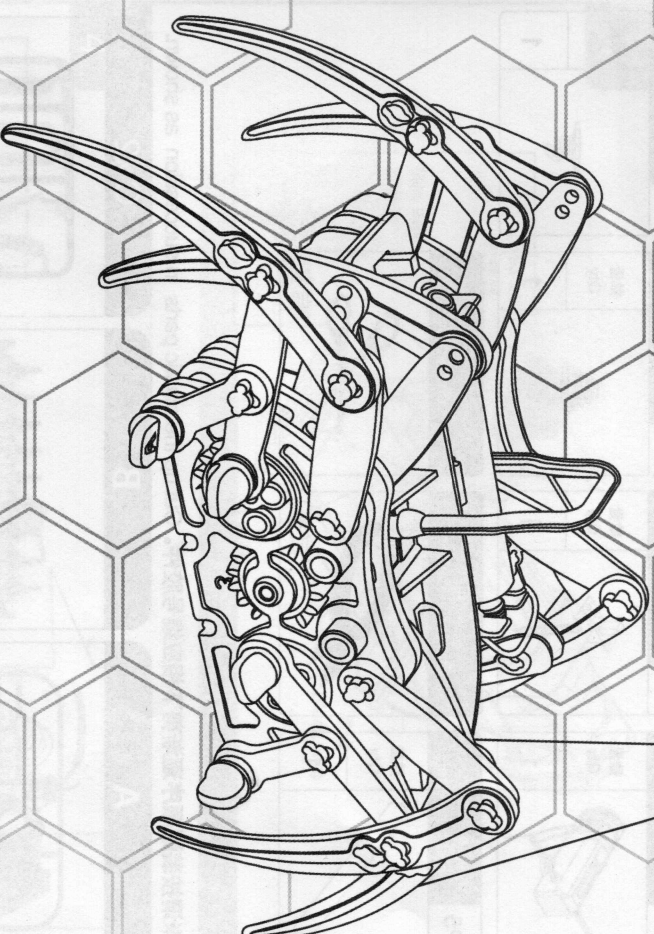
STEM
education

6+
AGES

Spider

HIGH SIMULATION DIY ROBOT

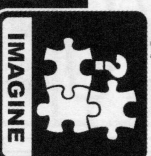
DIY
SCIENCE AND
EDUCATION
TOYS



ELECTRIC



PRACTICAL



IMAGINE



GAME, INSECT GAME

警告：
警告危险：含有细小物件，
不适合3岁以下的儿童使用

WARNING:
CHOKING HAZARD - small parts.
Not for children under 3 years



中国制造 MADE IN CHINA

- THIS IS A HIGHLY SIMULATED DIY SPIDER ROBOT.
- EIGHT GROSSED LEGS ACCURATELY REPRODUCE SPIDER REPTILES.
- TWO ASSEMBLY METHODS ALLOW YOU TO ASSEMBLE SPIDER ROBOTS WITH DIFFERENT PARTS AND STEPS.

产品介绍 Product Introduction

这是一款高仿真的DIY蜘蛛机器人，八条交叉的腿能精确地再现蜘蛛的爬行动作，两种组装方法可以让你组装出不同步伐和步态的蜘蛛机器人。孩子在组装的过程中可以体会到不断征服所带来的喜悦感和成就感，有助于孩子创新思维能力的培养和智力的开发。

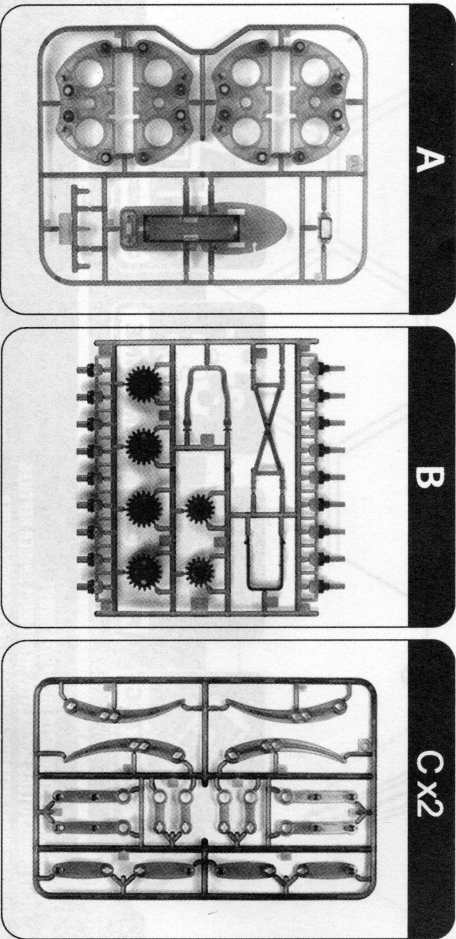
Spider Robot This is a kind of vivid DIY spider robot with eight multi-jointed legs accurately duplicate the walking movement of real spiders. There are two assembly choices for you to change the stride length and gait of the spider. Children can experience the joyance and achievement with the assembly, which can help to cultivate their innovation and intelligence.

机械零件清单和需要的工具 Mechanical Parts List & Tool You May Need:

P1 齿轮箱 Gear box 数量 Qty 1	P2 开关 Switch 数量 Qty 1	P3 接线端 Terminal 数量 Qty 1	P4 接线端 Terminal 数量 Qty 1
P5 橡胶管 Rubber tube 数量 Qty 1	剪刀 Diagonal Cutter (自备)	剪刀 Scissors (自备)	

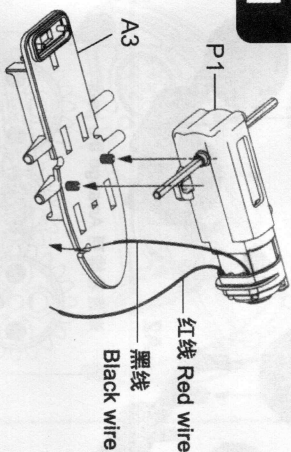
塑料零件 Plastic Parts:

※请按装配顺序逐渐剪下相应编号胶件。Cut up the plastic parts in succession as shown.

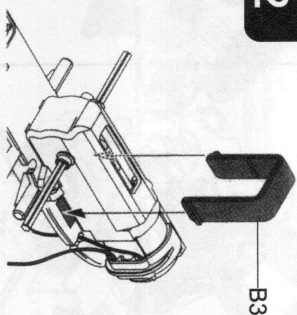


机械装配 Mechanical Assembly:

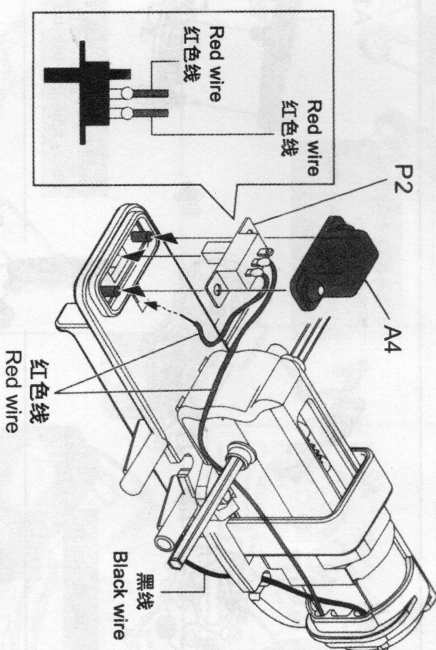
步骤STEP 1



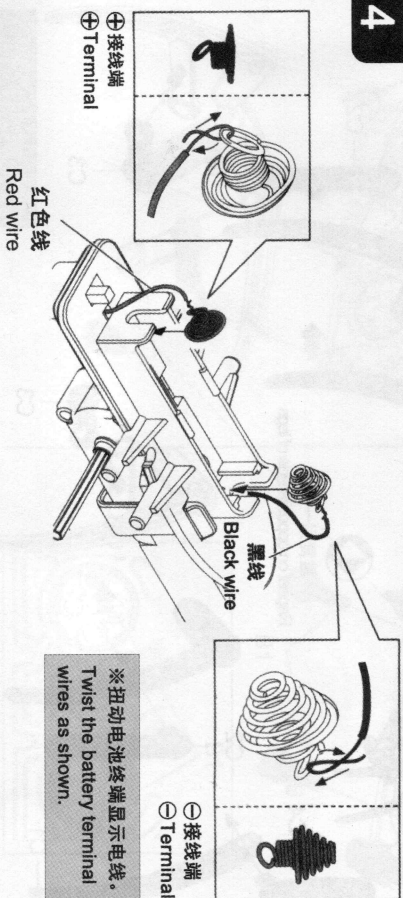
步骤STEP 2



步骤STEP 3



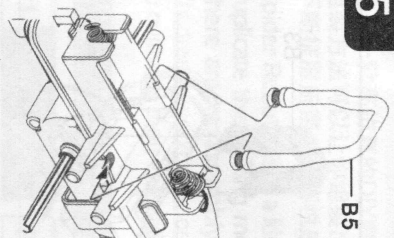
步骤STEP 4



※扭动电池终端显示电线。
Twist the battery terminal wires as shown.

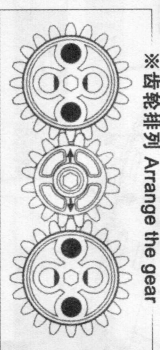
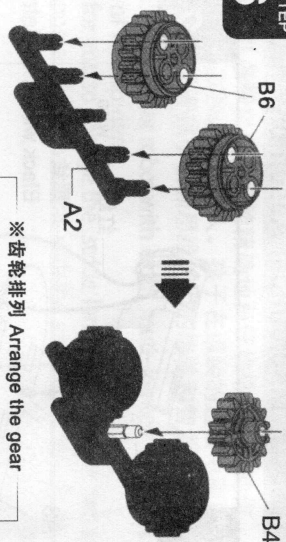
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步骤STEP



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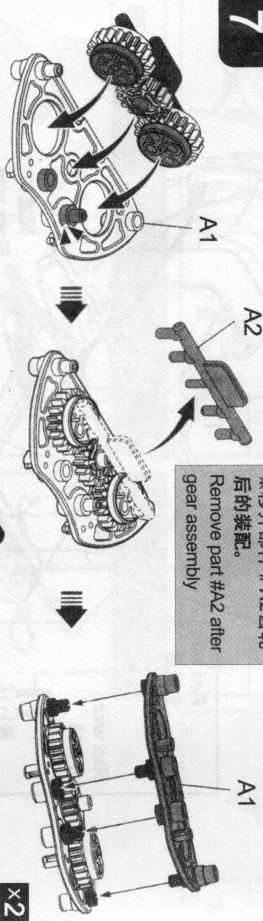
步骤STEP



※齿轮排列 Arrange the gear

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步骤STEP



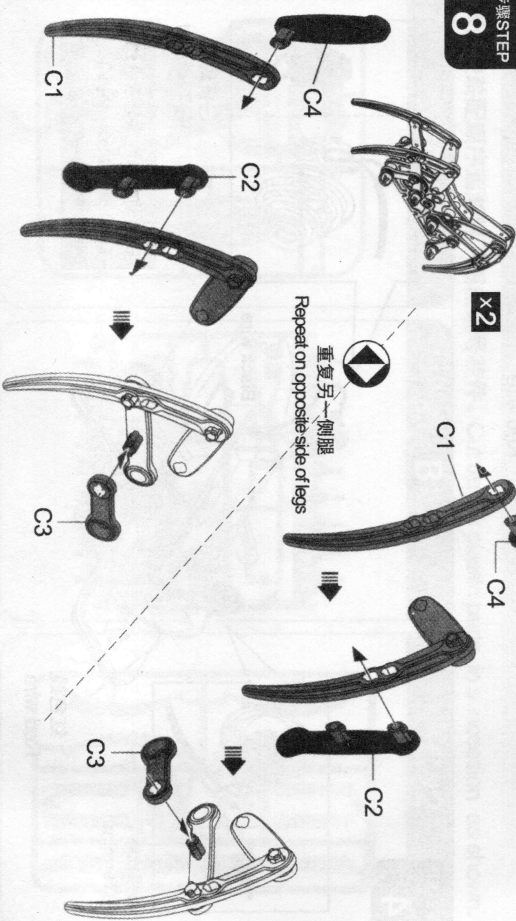
※移开部件 # A2 齿轮后的装配。
Remove part #A2 after gear assembly

※注意方向 Note the direction.

※组装齿轮的另一侧。
Assemble the second set of gears.

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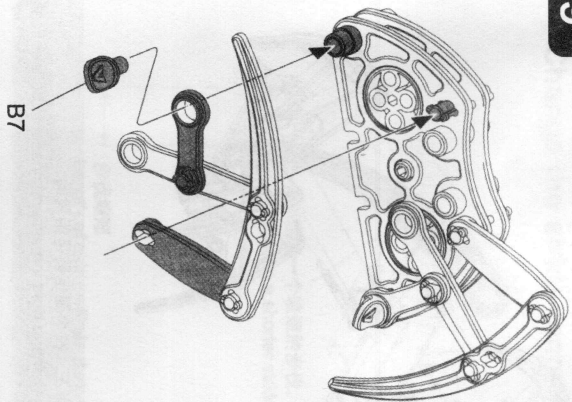
步骤STEP



重复另一侧腿
Repeat on opposite side of legs

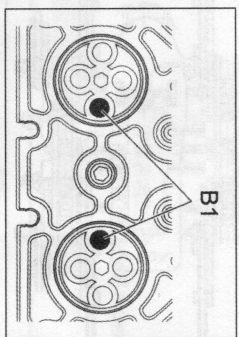
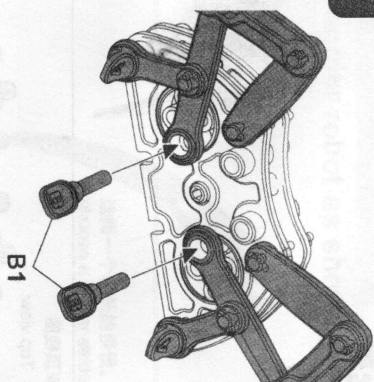
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步骤STEP



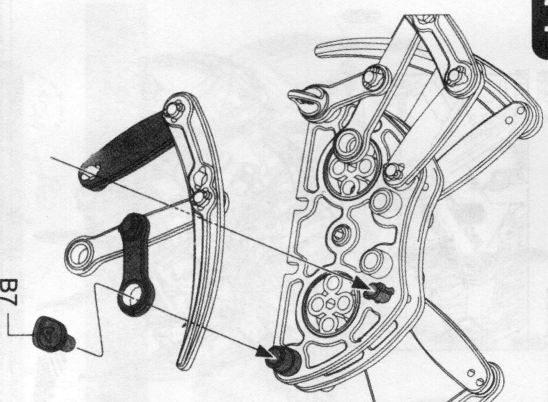
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步骤STEP



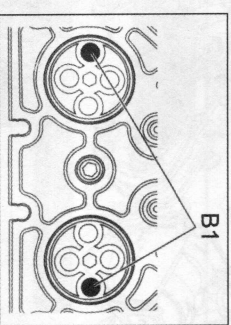
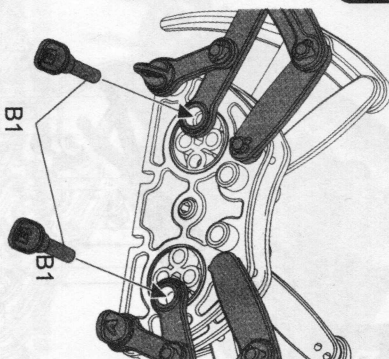
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步骤STEP



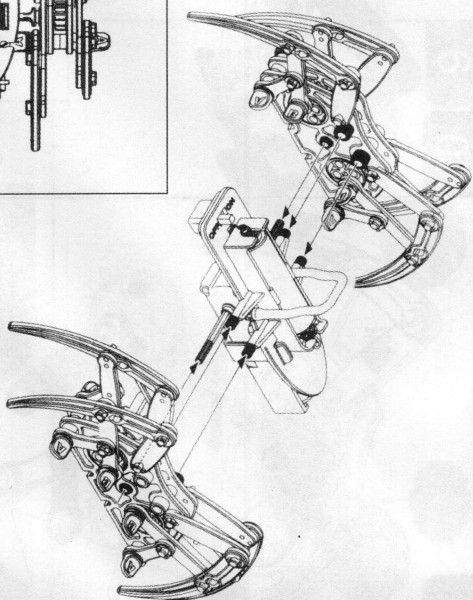
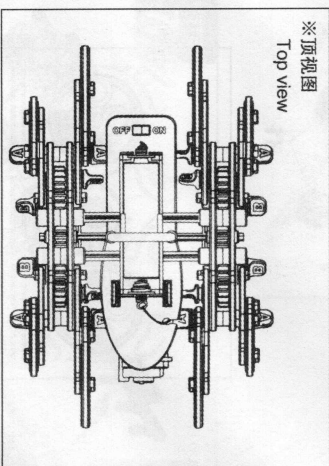
12

步骤STEP



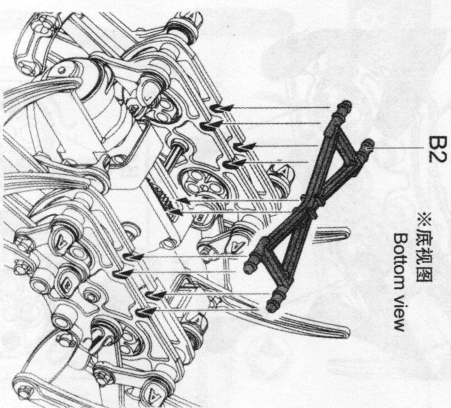
< 对面 Opposite side >

步骤STEP 13

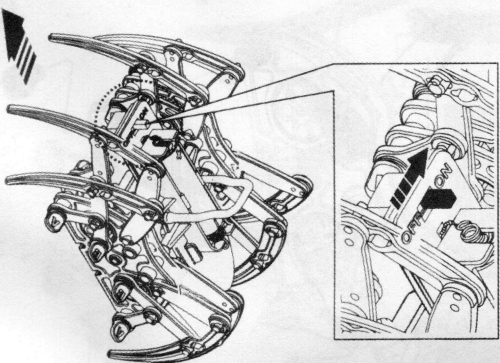


※左, 右小腿组装是相同的。
left and right leg assembly should be identical.

步骤STEP 14



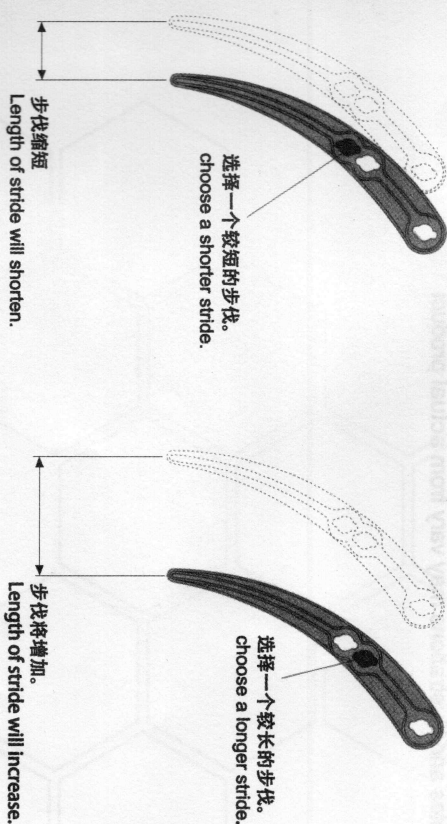
※如何开启
How to operate



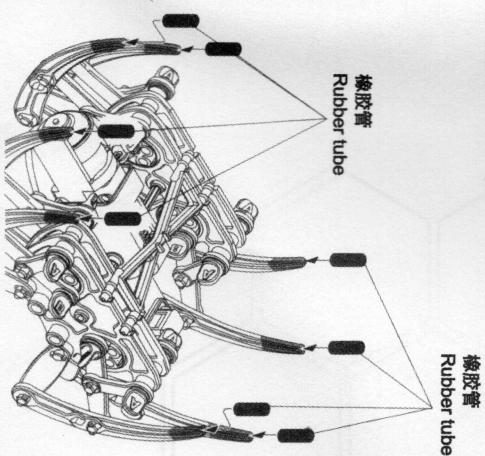
※如下所示移动开关到ON的位置, 开启蜘蛛的腿。
Move the switch to the ON position as shown to operate the spider's legs.

如下所示的蜘蛛机器人更改的步伐

Change the stride length for the spider robot as shown



插入橡胶管 Insert the rubber tube



※如果橡胶管连接到腿, 蜘蛛机器人可以爬缓坡。
Spider robot can climb gentle slopes if rubber tubes are attached to legs.

※切8个相同长度的橡胶管 (如图所示), 并连接到腿。
Cut the rubber tube in 8 equal lengths (as shown) and attach to legs

